

September 26: Reductive Groups

I. Definitions and Examples

II. Root Data; Existence and Isogeny Theorem

III. Representations of Reductive Groups.

I. Definitions and Examples

Definition An algebraic group G over a field k is a scheme of finite type $/k$ together with a morphism $m: G \times_G G \rightarrow G$ such that

- i) \exists maps $e: \text{Spec } k \rightarrow G$, $i: G \rightarrow G$ such that
- ii) the usual diagrams defining a group all commute.

"usual diagrams" e.g. $\begin{array}{ccc} G \times G \times G & \xrightarrow{id \times m} & G \times G \\ m \times id \downarrow & & \downarrow m \\ G \times G & \xrightarrow{m} & G \end{array}$

Associativity: (G, m) is an affine algebraic group if G is an affine scheme.

e.g. the multiplicative group $G_m = \text{Spec}(k[x, x^{-1}])$.

(G, m) is smooth, if G is a smooth (resp. connected) scheme - (resp. connected)

G is smooth iff some point $\text{Spec}(k) \rightarrow G$ is smooth.

All alg. groups are smooth if $\text{char. } k = 0$.

G is connected iff: $\begin{cases} G \text{ is geometrically connected, i.e. } G \times_{\bar{k}} \bar{k} \text{ is connected.} \\ G \text{ is irreducible.} \end{cases}$

Definition A group G/k is reductive if G is smooth, connected, and has trivial unipotent radical.

The unipotent radical of G is the maximal normal unipotent subgroup of G .

A ~~nilpotent~~ group U_k is unipotent if all homomorphisms $G \rightarrow GL(V)$ stabilize a vector of V .

The previous definitions require some proof; existence of a <sup>well-defined
maximal</sup> unipotent subgroup

• 3) nontrivial,

$\text{GL}(V)$ where $V \cong A_K^n$ is defined by $k[x_1, \dots, x_n, \det^{-1}]$.

An algebraic subgroup of G is a closed subscheme H of G together with the morphism $m|_{H \times H}$.

Examples • Classical groups GL_n, SL_n, SO_n , etc. are reductive.

- PGL_n is reductive.
- Spa has nontrivial unipotent radical ($= Gra$).
- Upper triangular matrices with diagonal of 1's has unipotent radical equal to itself.

Motivation for considering reductive groups

- In characteristic zero, reductive = linearly reductive; $\text{Rep}_{\mathbb{C}}$ is semisimple.
- No longer true in positive characteristic (e.g., $GL_p \cap V^{\otimes p}$ cannot split)

Definition A split torus over k is an algebraic group isomorphic to \mathbb{G}_m^n .

A torus is an algebraic group T also such that $T \times_{\mathbb{K}} \overline{k} \cong \mathbb{G}_m^n \overline{k}$.

Example: $G/\mathbb{R} : \text{Spec}(\frac{\mathbb{R}[x,y]}{(x^2+y^2-1)})$ is not split.

Definition A reductive group G is splittable if it contains a split torus.

A split reductive group is a pair (G, T) where G is splittable and T is a fixed split torus which is maximal.

Examples • $(GL_2, \{ \text{diagonal matrices} \})$ is a split reductive group.

- $(SL_2, \{ \text{diagonal matrices} \})$ is a split reductive group.
- $(SO_3, \{ \text{matrices fixing an axis of } SO_3 \cap k^3 \})$
- $(\text{compact group}/\mathbb{R}, \text{maximal torus})$ is reductive but not splittable.

There is a nice way to consider $\text{Lie}(G)$ for an algebraic group G/k .

II. Root data and Existence and Isogeny Theorem

Goal: Classify split reductive groups using combinatorial data.

Definition Let X, X^\vee be free \mathbb{Z} -modules with perfect pairing $\langle -, - \rangle : X \times X^\vee \rightarrow \mathbb{Z}$. If $\Phi \subseteq X$ is a finite set, ~~and~~ given a bijection $\Phi \rightarrow \Phi^\vee (\alpha \mapsto \alpha^\vee)$, we say $(X, \Phi, X^\vee, \Phi^\vee)$ is a root datum if

$$i) \langle \alpha, \alpha^\vee \rangle = 2$$

$$ii) \text{If } s_\alpha : X \rightarrow X \text{ is defined by } s_\alpha(x) = \alpha^\vee \langle x, \alpha^\vee \rangle$$

$$s_\alpha(x) = x - \langle x, \alpha^\vee \rangle, \text{ then } s_\alpha(\Phi) \subseteq \Phi$$

$$iii) \text{The group of automorphisms of } X \text{ generated by } \{s_\alpha\}_{\alpha \in \Phi} \text{ is finite.}$$

A root datum is reduced if $\mathbb{Q} \cdot \alpha \cap \Phi = \{\pm \alpha\}$.

Example (SL_2, T) Want to associate a root datum to a split reductive group.

Example (SL_2, T)

$$X = X^*(T) = \text{character lattice} = \frac{\mathbb{Z} X_1 + \mathbb{Z} X_2}{\langle X_1 + X_2 \rangle} \quad \text{where } a X_1 \left(\begin{smallmatrix} t_1 & \\ & t_2 \end{smallmatrix} \right) = t_1, \\ T \rightarrow \mathbb{G}_m. \qquad b X_2 \left(\begin{smallmatrix} t_1 & \\ & t_2 \end{smallmatrix} \right) = t_2.$$

$$X^\vee = X_*(T) = \text{cocharacter lattice } \mathbb{G}_m \rightarrow T = \{a_1 \lambda_1 + a_2 \lambda_2 \mid a_i \in \mathbb{Z}, a_1 + a_2 = 0\},$$

$$\text{Here } a_1 \lambda_1 + a_2 \lambda_2 : t \mapsto \left(\begin{smallmatrix} t^{a_1} & \\ & t^{a_2} \end{smallmatrix} \right).$$

$$\langle f, g \rangle = \text{fog} : \mathbb{G}_m \rightarrow SL_2 \rightarrow \mathbb{G}_m = \{l \in X^* \mid l \circ f \circ g = 1\}.$$

For Φ, Φ^\vee we use the Lie algebra.

$\text{Ad}: \text{SL}_2 \rightarrow \text{GL}(\text{sl}_2)$ (same definition for all groups).

Consider $g \mapsto (\text{conjugation by } g)$

We have

$$\text{Ad}\left(\begin{pmatrix} t_1 & 0 \\ 0 & t_2 \end{pmatrix}\right) \cdot \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = (\chi_1 - \chi_2) \begin{pmatrix} t_1 & 0 \\ 0 & t_2 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

The other basis vector gives $\chi_2 - \chi_1$.

$$\Phi := \{\chi_1 - \chi_2, \chi_2 - \chi_1\} = \text{the roots.}$$

$$\Phi^\vee = \{\lambda_1 - \lambda_2, \lambda_2 - \lambda_1\} \text{ (easy to see if we take them to pair to 2).}$$

Check: $(\chi_1 - \chi_2)(\lambda_1 - \lambda_2): t \mapsto \begin{pmatrix} t & \\ & t^{-1} \end{pmatrix} \mapsto t \cdot (t^{-1})^{-1} = t^2$;

similarly for the other one.

The automorphism condition is easy to show and left as an exercise.

Note A different (and perhaps more standard) way of writing this root datum is $(\mathbb{Z}e, \pm 2e, \mathbb{Z}e^*, \pm e^*)$ where $e = \chi_1 - \chi_2$, $e^* = \lambda_1 - \lambda_2$.

All four pieces of data in a root datum are important!

Example

$$G_m^{r+1} \times \text{SL}_2, G_m^{r+1} \times \text{PGL}_2, G_m^{r+2} \times \text{GL}_2$$

$$\text{Root data: } (\mathbb{Z}^r, \pm 2e_i, \mathbb{Z}, \pm e_i^*), (\mathbb{Z}^r, \pm e_i, \mathbb{Z}^r \pm 2e_i^*), (\mathbb{Z}^r, \pm (e_i + e_j), \mathbb{Z}^r, \pm (e_i^* + e_j^*)).$$

Langlands Dual Group (over \mathbb{C}).

G reductive group, the Langlands dual group G^\vee is the reductive group corresponding to the dual root datum $(X, \Phi, X^\vee, \Phi^\vee) \longleftrightarrow (X^\vee, \Phi^\vee, X, \Phi)$.

<u>Examples</u>	G	G^\vee
	SL_n	PGL_n
	$\text{SO}(2n+1)$	$\text{Sp}(2n)$
	$\text{SO}(2n)$	$\text{SO}(2n)$
	GL_n	GL_n

The notion makes sense because of the following theorem:

Theorem (Existence and Isogeny Theorem)

Category of ^{split}
Reductive groups $(G, T) \mapsto (X, \bar{\Phi}, X^\vee, \bar{\Phi}^\vee)$ Category of root data
ob: (G, T) \longmapsto ob: reduced root data
morphisms: isogenies $(G, T) \rightarrow (G', T')$ \longmapsto morphisms: isogeny of root data.
modulo $T'/Z(G)$

is an equivalence of categories.